High precision fluxgate AC/DC current transducer for galvanically isolated measurement up to 660 A

Features

- 424 A rms nominal current
- 10 V output at 600 A through BNC connector
- Ø27.6 mm aperture
- 70 ppm total accuracy
- 10 ppm linearity
- 10 ppm offset
- Status signal and LED

CE RoHS 2011/65/EU UK CA

Description

High precision DC current transducer (DCCT) measuring up to 660 A currents and continuously measuring 600 A currents with a linearity error less than 10 ppm.

Based on the ultra stable Danisense closed loop flux gate technology, the DS600UB-10V has very low offset and ultra low drift.

With an integrated voltage output module (VOM) outputting 10V at 600 A, the DS600UB-10V makes current measuring easy.

It provides high resolution for precise monitoring, reliable and consistent performance, and a rugged, full aluminium design for durability.

Applications

- Electric vehicle (EV) test bench
- Power measurement and power analysis
- Particle accelerators
- MRI devices and medical scanners
- Battery testing and evaluation systems
- Current calibration purposes
- Stable power supplies
- Precision current sensing

Electrical specifications at 23 °C, $V_S = \pm 15$ V supply voltage

Parameter		Symbol	Unit	Min	Typ.	Max	Comment
Nominal primary AC current		$I_{PN\ AC}$	Arms			424	Refer to Fig. 2 for derating
Nominal primary DC current		$I_{PN\ DC}$	A	-600		600	Refer to Fig. 2 for derating
Measuring range		I_{PM}	A	-660		660	Refer to Fig. 2 for derating
Overload capacity		I_{OL}	A			1500	Non-measured 100ms
Nominal secondary voltage		V_{SN}	V	-10		10	At nominal primary DC current
Transfer ratio		k	A/V	60		60	$I_{primary}/V_{secondary}$
Output resistance		R_O	Ω		0		At DC
Linearity error		ϵ_L	ppm	-10		10	ppm refers to reading
Ratio error			ppm	-50		50	ppm refers to reading
Ratio temperature coefficient			ppm/K	-3	± 1	3	ppm refers to reading
Ratio stability			ppm/month	-10		10	ppm refers to reading
Offset (including earth field)			ppm	-10		10	ppm refers to $I_{PN\ DC}$
Offset temperature coefficient			ppm/K	-0.2		0.2	ppm refers to $I_{PN\ DC}$
Offset stability over time			ppm/month	-0.2		0.2	ppm refers to $I_{PN\ DC}$
Bandwidth		$f(\pm 3\text{dB})$	kHz		300		Small signal. See Fig. 3
Response time to a step current I_{PN}		t_r	µs		1		To 90% of step current
Total accuracy without offset		ϵ_{tot}		*% of reading + % of full scale*			Full scale refers to $I_{PN\ DC}$.
	<10 Hz				0.0060 + 0.00005		For details, see Reading and full
	<100 Hz				0.0060 + 0.0001		scale
	<1 kHz				0.02 + 0.0002		For other frequencies, see Linear
	<10 kHz				0.1 + 0.0005		interpolation of accuracy
	<100 kHz				4 + 0.0025		specification.
	<300 kHz				30 + 0.005		
Phase shift	<10 Hz				0.01°		
	<100 Hz				0.01°		
	<1 kHz				0.03°		
	<10 kHz				0.2°		
	<100 kHz				4°		
RMS noise	<10 Hz		ppm rms		0.05	0.1	ppm refers to $I_{PN\ DC}$
	<100 Hz				0.07	0.15	
	<1 kHz				0.25	0.35	
	<10 kHz				0.8	1	
	<100 kHz				3.8	5	
Peak-to-peak noise	<10 Hz		ppm p-p			0.5	ppm refers to $I_{PN\ DC}$
	<100 Hz					1	
	<1 kHz					2	
	<10 kHz					5	
	<100 kHz					25	
Fluxgate excitation frequency		f_{exc}	kHz		31.25		
Power supply voltages			V	± 14.25		± 15.75	
Idle current consumption			mA		± 100		Primary current = 0 A
Current consumption at nominal current			mA	-500		500	At $I_{PN\ DC}$
Current consumption at max current			mA	-550		550	At I_{PM}
Offset change with external magnetic field			ppm/mT		5		ppm refers to nominal current
Offset change with power supply voltage changes			ppm/V	-0.4		0.4	ppm refers to nominal current

1 ppm nominal = 10 μV secondary voltage.

Linearity error

Linearity error is defined as the deviation from a straight line. The straight line is a linear regression trend line based on the least squares method of the measurement points from 0 to positive max current and another trendline is calculated from 0 to negative max current. The difference between each measured point and the linear trend line is the linearity error. The linearity error ϵ_L can be expressed as (1), where $I_{reading}$ is the measurement result and I_{fitted} is the regression value.

$$\epsilon_L = I_{reading} - I_{fitted} \tag{1}$$

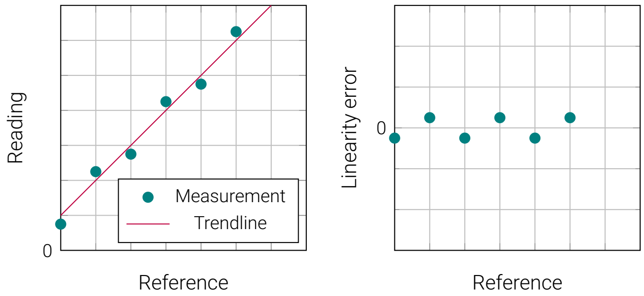

Figure 1: Linearity error definition

Reading and full scale

Reading is the actual value measured at a given time. Full scale is the rated nominal value of the device. If a given current $I_{reading}$ is measured, the total accuracy is calculated as (2). Example: A 500 A rated device has a specification of 0.005% + 0.0015% (reading + full scale) at < 10 Hz, plus an offset of 0.001 % (of full scale). The device is measuring (reading) 10 A dc, and the accuracy is calculated as (3).

$$\epsilon_{tot} = \epsilon_{reading} \cdot I_{reading} + (\epsilon_{fullscale} + \epsilon_{offset}) \cdot I_{PNDC} \tag{2}$$

$$\epsilon_{tot} = 0.005\% \cdot 10\text{A} + (0.0015\% + 0.001\%) \cdot 500\text{A} = 13\text{mA} \tag{3}$$

Primary and secondary current/voltage

The secondary current I_S or voltage V_S is calculated by using the transfer ratio k, as in (4).

$$I_S = \frac{I_P}{k}, \qquad V_S = \frac{I_P}{k} \tag{4}$$

Converting from ppm of nominal to secondary current/voltage

The nominal primary current is the rated current for the device. If ϵ_{ppm} is the error in ppm referred to nominal, use (5) to convert to ampere primary current. If the primary/secondary transfer ratio is k, use (6) to convert to ampere secondary current. If the device has voltage output, use (7)

$$\epsilon_{P_{ampere}} = \epsilon_{ppm} \cdot I_{PNDC} \cdot 1 \times 10^{-6} \tag{5}$$

$$\epsilon_{S_{ampere}} = \epsilon_{ppm} \cdot \frac{I_{PNDC}}{k} \cdot 1 \times 10^{-6} \tag{6}$$

$$\epsilon_{S_{volt}} = \epsilon_{ppm} \cdot \frac{I_{PNDC}}{k} \cdot 1 \times 10^{-6} \tag{7}$$

Linear interpolation of accuracy specification

If the accuracy at a specific frequency is required, it is possible to use linear interpolation between known points. If the frequency f is $f_1 < f < f_2$ and the accuracy at the frequency $\epsilon(f)$ is $\epsilon(f_1) < \epsilon(f) < \epsilon(f_2)$, then the accuracy at f is found as (8).

$$\epsilon(f) = \frac{\epsilon(f_2) - \epsilon(f_1)}{f_2 - f_1}(f - f_1) + \epsilon(f_1) \tag{8}$$

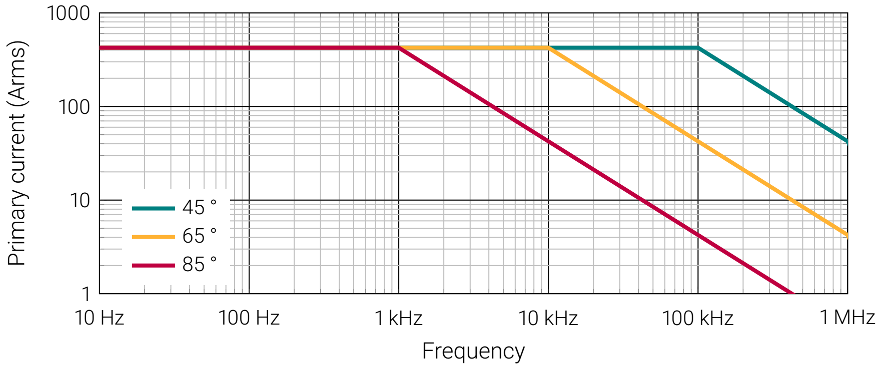

Figure 2: Maximum continuous primary current vs. frequency

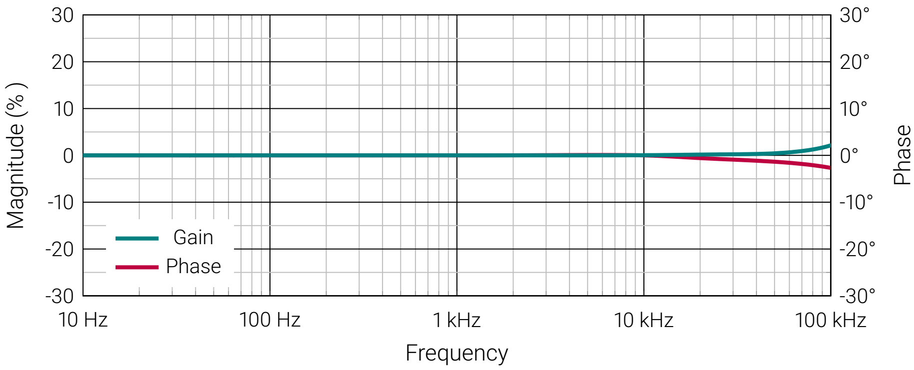

Figure 3: Frequency characteristics

Isolation specifications according to IEC 61010-1

⚠ When using *REINFORCED insulated* wire, all wiring must be insulated for the highest voltage used. When using *BASIC insulated* or *uninsulated* wire, follow the specified voltages in the table below:

Parameter		Unit	Value
Clearance		mm	9.5
Creepage distance		mm	10.5
Comparative tracking index (CTI)		V	> 600
Continuous working voltage according to IEC 61010-1 with:			
Uninsulated wire:	Non mains	V	1000
	CAT II (dc and rms)	V	600
	CAT III (dc and rms)	V	300
BASIC insulated wire:	Non mains	V	2000
	CAT II (dc and rms)	V	1000
	CAT III (dc and rms)	V	1000
Transient voltage according to IEC 61010-1 with:			
Uninsulated wire:	Non mains	V	4500
	CAT II	V	6000
	CAT III	V	6000
BASIC insulated wire:	Non mains	V	6500
	CAT II	V	6000
	CAT III	V	8000

⚠ Do not connect the transducer to signals or use for measurements within Measurement Category IV, or for measurements on MAINs circuits or on circuits derived from Overvoltage Category IV which may have transient overvoltages above what the product can withstand. The product must not be connected to circuits that have a maximum voltage above the continuous working voltage, relative to earth or to other channels, or this could damage and defeat the insulation.

Environmental and mechanical characteristics

Parameter	Unit	Min	Typ	Max	Comment
Altitude	m			2000	
Usage					Designed for indoor use
Pollution degree				2	
Operating temperature range	°C	-40		85	
Storage temperature range	°C	-40		85	
Relative humidity	%	20		80	Non-condensing
Ingress protection rating				IP20	
Mass	kg		0.6		

Connections:	D-sub-9 power supply and BNC voltage reading
EMC:	EN 61326-1:2013-2021
Safety:	IEC 61010-2-030:2021/A11:2021 and IEC 61010-1:2010/A1:2019

External devices:	External devices connected to current transducers must comply with the standards IEC61010-1 and IEC62368-1 and be energy-limited circuitry
Cleaning:	The transducer should only be cleaned with a damp cloth. No detergent or chemicals should be used.
Temperature:	When multiple primary turns are used or high primary currents are applied the temperature around the transducer will increase, please monitor to ensure that the maximum ratings are not exceeded. It is recommended to have minimum 1 mm^2 per ampere in the primary bus bar.

Intended use

The DS600UB-10V is designed to measure current up to 660 A, and be powered by a DSSIU-4-1U or DSSIU-6-1U or similar power supplies. Please see the product manual: https://danisense.com/user-manual.

Instruction for use

⚠ Please follow the polarity of the voltage supply to avoid damaging the device. See Fig. 4.

1. Do not power up the device before all cables are connected.
2. Place the primary conductor through the aperture of the transducer.
3. Connect a D-sub-9 cable between DSSIU-4/6-1U and each sensor.
4. When all connection are secured - connect mains power.
5. Apply primary current and measure the output voltage on the BNC connector.

⚠ There is a risk of electrical shock if an uninsulated busbar with high voltages is touching the metal en- closure of the transducer. Please ensure, before powering up the system, that no uninsulated wire can touch the metal enclosure.

Pin out description

1	DO NOT USE	Must not be connected
2	NC	No connection
3	Status-	Status signal negative terminal
4	0 V	0 V connection for supply voltage
5	V_S-	Negative supply voltage
6	DO NOT USE	Must not be connected
7	NC	No connection
8	Status+	Status signal positive terminal
9	V_S+	Positive supply voltage

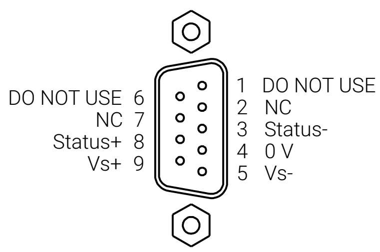

Figure 4: D-sub-9 connection pinout

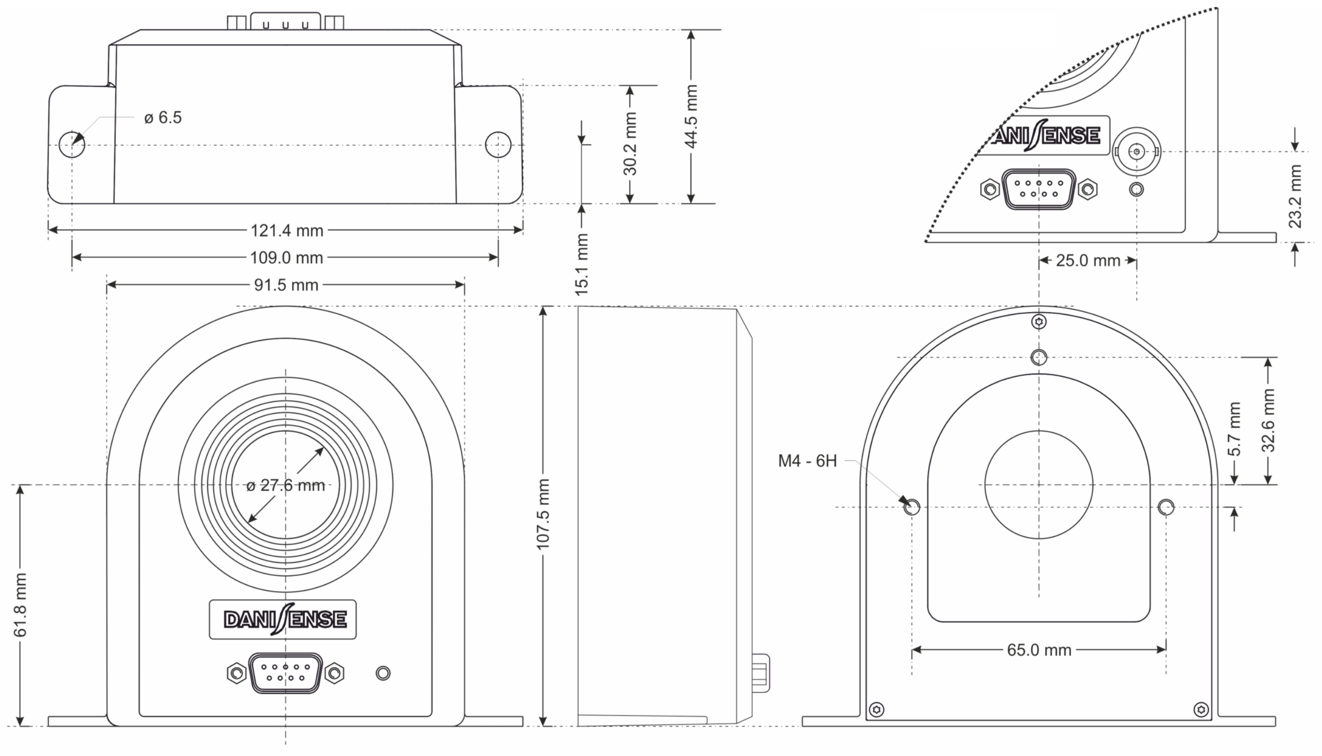

Figure 5: Dimensions of sensor head. Tolerance is 0.3 mm

Mounting instructions

Base plate:	2 x M5 holes, 6 Nm
Back side:	3 x M4 threaded holes, 4 Nm

Positive current direction

Is identified by an arrow on the back side isolation plastic insert.

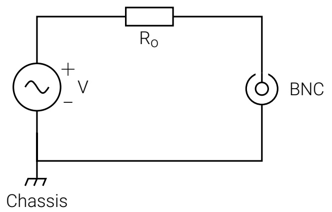

Figure 6: BNC shield and chassis connection

Status signal and LED

When the sensor is operating in normal condition the status pins (Status+ and Status-) are shorted by an optocoupler and the green status LED is ON, see Fig. 7. When a fault is detected, or the power is off, the status pins are opened and the green status LED is OFF. Status signal optocoupler ratings found below:

Forward direction:	Status+ to Status- (Pin 8 to pin 3)
Maximum forward current:	10 mA
Maximum forward voltage:	60 V
Maximum reverse voltage:	5 V

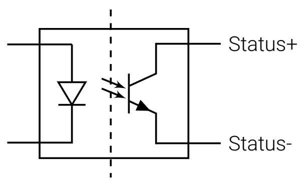

Figure 7: Status signal optocoupler

⚠ Do not disassemble the unit. If the green status LED is not operating with all cables connected and the system powered up, disconnect power and contact Danisense for further instruction. If the equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

Declaration of Conformity

Danisense A/S
Malervej 10
DK-2630 Taastrup
Denmark

Declares that under our sole responsibility that this product is in conformity with the provisions of the following EC Directives, including all amendments, and with national legislation implementing these directives:

Directive 2014/30/EU

Directive 2014/35/EU

And that the following harmonized standards have been applied

EEN 61010-1 (Third Edition):2010, EN 61010-1:2010/A1:2019

EN 61010-2-030:2021/A11:2021

EN 61326-1:2013

All DANISENSE products are manufactured in accordance with RoHS directive 2011/65/EU. Annex II of the RoHS directive was amended by directive 2015/863 in force since 2015, expanding the list of 6 restricted substances (Lead, Hexavalent Chromium, PBB, PBDE and Cadmium)

Danisense follows the provision in EN 63000:2018

Place		Date
Taastrup, Denmark	Henrik Elbæk	2022-03-15