# Kübler

## Absolute encoders – multiturn

# Standard mechanical multiturn, optical

Sendix 5868 / 5888 (shaft / hollow shaft)

**CANopen/CANopenLift** 



The Sendix multiturn encoders 5868 and 5888 with CANopen or CANopenLift interface and optical sensor technology are the right encoders for all CANopen or CANopenLift applications.

With a maximum resolution of 28 bits these encoders offer an optional additional RS422 incremental track with 2048 pulses.























Mechanical drive

Safety-Lock<sup>T</sup>

High rotational

Temperature range

High pi le

ection High shaft lo el capacity

shaft load Mag apacity

Magnetic field proof

resistant

Reverse polarity

SINCO

### Reliable

- Tried-and-tested in applications with the highest demands, such as in mobile automation or medical technology.
- Ideal for use outdoors thanks to IP67 protection and wide temperature range from -40°C up to +80°C.

### **Flexible**

- Node address can be set via rotary switches or software.
- Baud rate and termination can be set via DIP switches or software
- With bus terminal cover or fixed connection, as well as M12 connectors or cable connection.

e Fieldbus profile

1 Options (service)

2 = no options

3 = SET button

221 = CANIift DS417 V1.01

212 = CANopen encoder profile DS406 V3.2

• Universal scaling function.

## Order code Shaft version

8.5868 Type



If for each parameter of an encoder the **underlined preferred option** is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



## a Flange

1 = clamping flange, IP65 ø 58 mm [2.28"]

3 = clamping flange, IP67 ø 58 mm [2.28"]

2 = synchro flange, IP65 ø 58 mm [2.28"]

4 = synchro flange, IP67 ø 58 mm [2.28"]

5 =square flange, IP65  $\square$  63.5 mm [2.5"]

7 = square flange, IP67 ☐ 63.5 mm [2.5"]

## **b** Shaft (ø x L), with flat

1 = 6 x 10 mm [0.24 x 0.39"] 1)

2 = 10 x 20 mm [0.39 x 0.79"] 2)

3 = 1/4" x 7/8"

4 = 3/8" x 7/8"

#### © Interface / power supply

2 = CANopen DS301 V4.02, 10 ... 30 V DC

5 = CANopen DS301 V4.02, 10 ... 30 V DC

with 2048 ppr incremental track (TTL-compatible) 3)

Type of connection

removable bus terminal cover

I = radial cable gland

## $2 = 2 \times \text{ or } 3 \times \text{M12 connector, 5-pin}$

Fixed connection without bus terminal cover

 $A = radial \ cable, 2 \ m \ [6.56'] \ PVC$ 

B = radial cable, special length PVC \*)

E = 1 x radial M12 connector, 5-pin

F = 2 x radial M12 connector, 5-pin I = 1 x radial M23 connector, 12-pin

 $J = 1 \times radial M23$  connector, 12-pin  $J = 2 \times radial M23$  connector, 12-pin

K = 1 x Sub-D connector, 9-pin

\*) Available special lengths (connection type B): 3, 5, 8, 10, 15 m [9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.5868.112B.2123.0030 (for cable length 3 m)

#### Optional on request

- Ex 2/22 4
- surface protection salt spray tested
- seawater resistant (stainless steel V4A)

Salt spray tested / stainless steel V4A as standard types (deliverable as from 1 unit)



salt spray tested: 8.5868.3222.2122-C



stainless steel V4A: 8.5868.3222.2122-V4A

399

<sup>1)</sup> Preferred type only in conjunction with flange type 2.

<sup>2)</sup> Preferred type only in conjunction with flange type 1.

<sup>3)</sup> Only in conjunction with connection type 2.4) For the cable connection type, cable material PUR.



## **Standard** mechanical multiturn, optical

## Sendix 5868 / 5888 (shaft / hollow shaft)

## CANopen/CANopenLift

## Order code **Hollow shaft**

8.5888



If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces.  ${\tt Qts.}\ {\tt up}\ {\tt to}\ {\tt 50}\ {\tt pcs.}\ {\tt of}\ {\tt these}\ {\tt types}\ {\tt generally}\ {\tt have}\ {\tt a}\ {\tt delivery}\ {\tt time}\ {\tt of}\ {\tt 15}\ {\tt working}\ {\tt days}.$ 



### a Flange

- 1 = with spring element, long, IP65
- 2 = with spring element, long, IP67
- 3 = with stator coupling, IP65 ø 65 mm [2.56"]
- 4 = with stator coupling, IP67 ø 65 mm [2.56"]
- 5 = with stator coupling, IP65 ø 63 mm [2.48"]
- 6 = with stator coupling, IP67 ø 63 mm [2.48"]
- **b** Blind hollow shaft

(insertion depth max. 30 mm [1.18"])

- 3 = Ø 10 mm [0.39"]
- 4 = ø 12 mm [0.47"]
- $5 = \emptyset 14 \text{ mm } [0.55"]$
- 6 = Ø 15 mm [0.59"]
- $8 = \emptyset 3/8"$
- $9 = \emptyset 1/2"$
- © Interface / power supply
- 2 = CANopen DS301 V4.02, 10 ... 30 V DC
- 5 = CANopen DS301 V4.02, 10 ... 30 V DC with 2048 ppr incremental track (TTL-compatible) 1)

Type of connection

removable bus terminal cover

- 1 = radial cable gland
- 2 = M12 connector, 5-pin
  - Fixed connection without bus terminal cover
- A = radial cable, 2 m [6.56'] PVC
- B = radial cable, special length PVC \*)
- E = 1 x radial M12 connector, 5-pin
- F = 2 x radial M12 connector, 5-pin
- I = 1 x radial M23 connector, 12-pin
- J = 2 x radial M23 connector, 12-pin
- $K = 1 \times Sub-D$  connector, 9-pin
- Available special lengths (connection type B): 3, 5, 8, 10, 15 m [9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.5888.542B.2123.0030 (for cable length 3 m)

### Optional on request

- Ex 2/22 2)
- surface protection salt spray tested
- seawater resistant (stainless steel V4A)

Fieldbus profile

212 = CANopen encoder profile DS406 V3.2

221 = CANIft DS417 V1.01

Options (service)

2 = no options

3 = SET button

Salt spray tested / stainless steel V4A as standard types (deliverable as from 1 unit)



salt spray tested: 8.5888.2422.2122-C 8.5888.2522.2122-C

V4A

stainless steel V4A: 8.5888.2422.2122-V4A

Mounting accessory for shaft encoders		Order no.
Coupling	bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"] bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	8.0000.1102.0606 8.0000.1102.1010
Mounting accessory for hollow shaft encoders	Dimensions in mm [inch]	Order no.
Cylindrical pin, long	with fixing thread	8.0010.4700.0000
for flange with spring element (flange type 1 + 2)	8[0,31] 5[0,2] SW7 [0,28] SW7 [0,28] SW7 [0,28]	
Connection technology		Order no.
Cordset, pre-assembled	M12 female connector with coupling nut for bus in, 5-pin 5 m [16.40'] PVC cable	05.00.6091.A211.005M
	M12 male connector with external thread for bus out, 5-pin 5 m [16.40'] PVC cable	05.00.6091.A411.005M
Connector, self-assembly (straight)	M12 female connector with coupling nut for bus in, 5-pin M12 male connector with external thread for bus out. 5-pin	8.0000.5116.0000 8.0000.5111.0000

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories. Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection\_technology.

<sup>1)</sup> Only in conjunction with connection type 2.

<sup>2)</sup> For the cable connection type, cable material PUR.



Standard mechanical multiturn, optical Sendix 5868 / 5888 (shaft / hollow shaft) **CANopen/CANopenLift** 

## Technical data

Mechanica	l characteristics	
Maximum spe	ed	
	IP65 up to 70°C [158°F]	9000 min <sup>-1</sup> , 7000 min <sup>-1</sup> (continuous)
	IP65 up to Tmax	7000 min <sup>-1</sup> , 4000 min <sup>-1</sup> (continuous)
	IP67 up to 70°C [158°F]	8000 min <sup>-1</sup> , 6000 min <sup>-1</sup> (continuous)
	IP67 up to T <sub>max</sub>	6000 min <sup>-1</sup> , 3000 min <sup>-1</sup> (continuous)
Starting torque	e - at 20°C [68°F] IP65	< 0.01 Nm
	IP67	< 0.05 Nm
Mass moment	of inertia	
	shaft version	4.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
	hollow shaft version	7.5 x 10 <sup>-6</sup> kgm <sup>2</sup>
Load capacity	of shaft radial	80 N
	axial	40 N
Weight	with bus terminal cover	approx. 0.57 kg [20.11 oz]
	with fixed connection	approx. 0.52 kg [18.34 oz]
Protection acc	c. to EN 60529	
	housing side	IP67
	shaft side	IP65, opt. IP67
Working temp	erature range	-40°C +80°C [-40°F +176°F] <sup>1)</sup>
Material	shaft/hollow shaft	stainless steel
	flange	aluminum
	housing	zinc die-cast
	cable	PVC (PUR for Ex 2/22)
Shock resista	nce acc. to EN 60068-2-27	2500 m/s <sup>2</sup> , 6 ms
Vibration resis	tance acc. to EN 60068-2-6	100 m/s², 55 2000 Hz

Electrical characteristics			
Power supply	10 30 V DC		
Power consumption (no load)	max. 100 mA		
Reverse polarity protection of the power supply	yes		
UL approval	file 224618		
CE compliant acc. to	EMC guideline 2014/30/EU RoHS guideline 2011/65/EU		

Interface characteristics CANopen/CANopenLift  Resolution singleturn  1 65536 (16 bit), scalable default: 8192 (13 bit)  Number of revolutions (multiturn)  max. 4096 (12 bit) scalable only via the total resolution  Total resolution  1 268.435.456 (28 bit), scalable default: 33.554.432 (25 bit)  Code  binary  Interface  CAN high-speed acc. to ISO 11898, Basic- and Full-CAN CAN specification 2.0 B  Protocol  CANopen profile DS406 V3.2 with manufacturer-specific add-ons or CANlift profile DS417 V1.1  Baud rate  10 1000 kbit/s can be set via DIP switches, software configurable  Node address  1 127 can be set via rotary switches, software configurable  Termination switchable  can be set via DIP switches, software configurable		
Default: 8192 (13 bit)   Number of revolutions (multiturn)   max. 4096 (12 bit)   scalable only via the total resolution	Interface characteristics CANo	pen/CANopenLift
Total resolution  1 268.435.456 (28 bit), scalable default: 33.554.432 (25 bit)  Code  binary  Interface  CAN high-speed acc. to ISO 11898, Basic- and Full-CAN CAN specification 2.0 B  Protocol  CANopen profile DS406 V3.2 with manufacturer-specific add-ons or CANlift profile DS417 V1.1  Baud rate  10 1000 kbit/s can be set via DIP switches, software configurable  Node address  1 127 can be set via rotary switches, software configurable  Termination switchable  can be set via DIP switches,	Resolution singleturn	
default: 33.554.432 (25 bit)  Code binary  Interface CAN high-speed acc. to ISO 11898, Basic- and Full-CAN CAN specification 2.0 B  Protocol CANopen profile DS406 V3.2 with manufacturer-specific add-ons or CANlift profile DS417 V1.1  Baud rate 10 1000 kbit/s can be set via DIP switches, software configurable  Node address 1 127 can be set via rotary switches, software configurable  Termination switchable can be set via DIP switches,	Number of revolutions (multiturn)	, ,
Interface  CAN high-speed acc. to ISO 11898, Basic- and Full-CAN CAN specification 2.0 B  Protocol  CANopen profile DS406 V3.2 with manufacturer-specific add-ons or CANlift profile DS417 V1.1  Baud rate  10 1000 kbit/s can be set via DIP switches, software configurable  Node address  1 127 can be set via rotary switches, software configurable  Termination switchable  can be set via DIP switches,	Total resolution	
Basic- and Full-CAN CAN specification 2.0 B  Protocol  CANopen profile DS406 V3.2 with manufacturer-specific add-ons or CANlift profile DS417 V1.1  Baud rate  10 1000 kbit/s can be set via DIP switches, software configurable  Node address  1 127 can be set via rotary switches, software configurable  Termination switchable  can be set via DIP switches,	Code	binary
with manufacturer-specific add-ons or CANlift profile DS417 V1.1  Baud rate 10 1000 kbit/s can be set via DIP switches, software configurable  Node address 1 127 can be set via rotary switches, software configurable  Termination switchable can be set via DIP switches,	Interface	Basic- and Full-CAN
Can be set via DIP switches, software configurable  Node address  1 127 can be set via rotary switches, software configurable  Termination switchable  can be set via DIP switches,	Protocol	with manufacturer-specific add-ons
can be set via rotary switches, software configurable  Termination switchable can be set via DIP switches,	Baud rate	can be set via DIP switches,
	Node address	can be set via rotary switches,
	Termination switchable	

Incremental track characteristics			
Output driver		RS422 (TTL-compatible)	
Permissible load / channel max. +/- 20 mA			
Signal level	HIGH	typ. 3.8 V	
	LOW	typ. 1.3 V	
Short circuit proof outputs yes <sup>2)</sup>			
Resolution		2048 ppr	

## SET button (zero or defined value, option)

Protection against accidental activation. Button can only be operated with a ball-pen or pencil.

## Diagnostic LED (yellow)

## LED is ON with the following fault conditions

Sensor error (internal code or LED error) too low voltage, over-temperature

Cable version: -30°C ... +75°C [-22°F ... +167°F].
 Short circuit to 0 V or to output, only one channel at a time, power supply correctly applied.



Standard mechanical multiturn, optical

Sendix 5868 / 5888 (shaft / hollow shaft)

CANopen/CANopenLift

#### General information about CANopen / CANopenLift

The CANopen encoders support the latest CANopen communication profile according to DS301 V4.02. In addition, device specific profiles such as encoder profile DS406 V3.2 and DS417 V1.1 (for lift applications) are available

The following operating modes may be selected: Polled Mode, Cyclic Mode, Sync Mode. Moreover, scale factors, preset values, limit switch values and many other additional parameters can be programmed via the CAN bus.

When switching the device on, all parameters are loaded from an EEPROM, where they were saved previously to protect them against power-failure.

The following output values may be combined in a freely variable way as PDO (PDO mapping): position, speed, acceleration as well as the status of the working area.

As competitively priced alternatives, encoders are also available with a connector or a cable connection, where the device address and baud rate can be changed and configured by means of the software. The models with bus terminal cover and integrated T-coupler allow for extremely simple installation: the bus and power supply can be easily connected via M12 connectors. The device address can be set via 2 rotary hex switches. Furthermore, another DIP switch allows for the setting of the baud rate and switching on a termination resistor. Three LEDs located on the back indicate the operating or fault status of the CAN bus, as well as the status of an internal diagnostic.

#### **Universal Scaling Function**

At the end of the physical resolution of an encoder, **when scaling is active**, an error appears if the division of the physical limit (GP\_U) by the programmed total resolution (TMR) does not produce an integer.

The Universal Scaling Function remedies this problem.

## CANopen communication profile DS301 V4.02

Among others, the following functionality is integrated.

- · Class C2 functionality.
- NMT slave.
- · Heartbeat protocol.
- · High resolution sync protocol.
- · Identity object.
- Error behavior object.
- Variable PDO mapping.
- · Self-start programmable (power on to operational).
- · 3 Sending PDO's.
- Node address, baud rate and CANbus.
- Programmable termination.

#### CANopen Encoder Profile DS406 V3.2

The following parameters can be programmed:

- · Event mode.
- Units for speed selectable (steps/sec or min-1).
- Factor for speed calculation (e.g. circumference of measuring wheel).
- Integration time for the speed value from 1 ... 32.
- 2 working areas with 2 upper and lower limits and the corresponding output states.
- Variable PDO mapping for position, speed, work area status.
- Extended failure management for position sensing with integrated temperature control.
- · User interface with visual display of bus and failure status 3 LED's.
- Optional 32 CAMs programmable.
- Customer-specific memory 16 Bytes.

## **CANopen Lift Profile DS417 V1.1**

Among others, the following functionality is integrated:

- · Car position unit.
- · 2 virtual devices.
- 1 virtual device delivers the position in absolute measuring steps (steps).
- 1 virtual device delivers the position as an absolute travel information in mm.
- · Lift number programmable.
- $\bullet$   $\,$  Independent setting of the node address in relation with the CAN identifier.
- Factor for speed calculation (e.g. measuring wheel periphery).
- Integration time for speed value of 1...32.
- 2 work areas with 2 upper and lower limits and the corresponding output states.
- · Variable PDO mapping for position, speed, acceleration, work area status.
- Extended failure management for position sensing with integrated temperature control.
- User interface with visual display of bus and failure status 3 LED's.
- "Watchdog controlled" device.

All profiles stated here: Key-features

The object 6003h "Preset" is assigned to an integrated key, accessible from the outside.



Standard mechani	l cal multiturn, c	optical		Sendix !	5868 / 58	188 (shaf	ft / hollo	w shaft)	CANope	n/CANo	penLift
Terminal as:	signment										
Interface	Type of connection	Cable gland (bu	s terminal c	over with te	erminal box	)					
		-			Bus OUT				Bus IN		
2, 5	1	Signal:	CAN_GND	CAN_L	CAN_H	0 V power supply	+V power supply	0 V +V power supply power su	CAN_L	CAN_H	CAN_GND
		Abbreviation:	CG	CL	СН	0 V	+V	0 V +V	CL	СН	CG
Interface	Type of connection	Cable (isolate u	nused wires	individuall <sup>a</sup>	y before ini	tial start-up	)				
					Bus IN						
2, 5	А, В	Signal:	0 V power supply	+V power supply	CAN_L	CAN_H	CAN_GND				
		Cable color:	WH	BN	YE	GN	GY				
Interface	Type of connection	2 x M12 connec	tor, 5-pin (3	x M12 coni	nector with Bus OUT	interface 5	)				
		Signal:	0 V	+V	CAN L	CAN_H)	CAN_GND	2		_1	
		Oigilai.		power supply	_	OAN_III	OAIV_GIVD			-4	
2, 5	2, F	Pin:	3	2	5	4	1	5		`3	
2, 3	2,1				Bus IN			] :	2	<b>1</b>	
		Signal:	0 V power supply	+V power supply	CAN_L	CAN_H	CAN_GND	:	3		
		Pin:	3	2	5	4	1		4	5	
					remental tr		l		1	2	
5	2	Signal:	Α	Ā	В	B	0 V		1	-3	
		Pin:	1	2	3	4	5		4	`5	
Interface	Type of connection	1 x M12 connec	tor. 5-pin								
	71		Bus IN 2 1								
2, 5	E	Signal:	0 V power supply	+V power supply	CAN_L	CAN_H	CAN_GND	:	3 (6)	,	
		Pin:	3	2	5	4	1		4	5	
Interface	Interface Type of connection 2 x M23 connector, 12-pin										
					Bus OUT						
		Signal:	0 V power supply	+V power supply	CAN_L	CAN_H	CAN_GND	,	1 9 8		
2, 5	J	Pin:	10	12	2	7	3	2 x	10 12	7))	
		Signal:	0 V	+V power supply	Bus IN CAN_L	CAN_H	CAN_GND	(	11 6		
		Pin:	10	12	2	7	3				
						l					
Interface	Type of connection	1 x M23 connec	tor, 12-pin					I			
		Cianal:	0.1/	+V	Bus IN	CAN	CAN CND		1 0 0	\	
2, 5	I	Signal:		power supply		CAN_H	CAN_GND		2 40 42	7	
		Pin:	10	12	2	7	3	(	3 10 12 11 6 4 5 5		
Interface	Type of connection	Sub-D connecto	or, 9-pin		Bus IN						
2, 5	K	Signal:	0 V	+V power supply	CAN_L	CAN_H	CAN_GND		1 2 3 4	5	
		Pin:	6	9	2	7	3		6 7 8 9		
	1	I	-	-	I	ı	_	I			



# Standard mechanical multiturn, optical

Sendix 5868 / 5888 (shaft / hollow shaft)

CANopen/CANopenLift

### Dimensions shaft version, with removable bus terminal cover

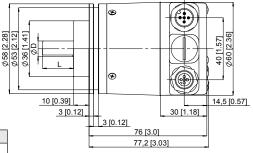
Dimensions in mm [inch]

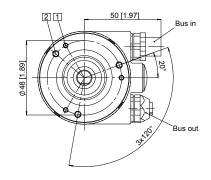
### Clamping flange, ø 58 [2.28] Flange type 1 and 3

(drawing with 2 x M12 connector)

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.32] deep





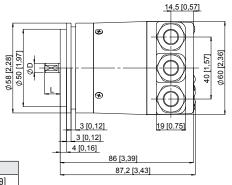
D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"

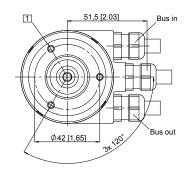
## Synchro flange, ø 58 [2.28]

### Flange type 2 and 4

(drawing with cable)

1 3 x M4, 6 [0.24] deep





D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"

Square flange,  $\square$  63.5 [2.5] Flange type 5 and 7

(drawing with cable)

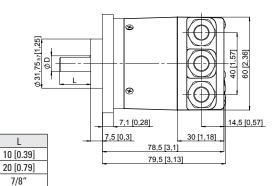
D

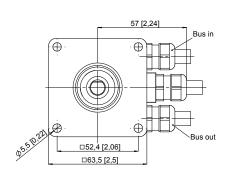
6 [0.24]

10 [0.39]

1/4"

3/8"





Fit

h7

f7

h7

h7



# Standard mechanical multiturn, optical

Sendix 5868 / 5888 (shaft / hollow shaft)

CANopen/CANopenLift

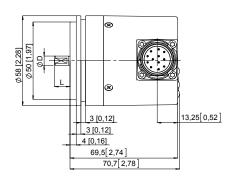
### Dimensions shaft version, with fixed connection

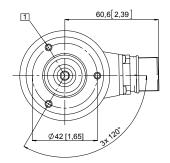
Dimensions in mm [inch]

#### Synchro flange, ø 58 [2.28] Flange type 2 and 4

(drawing with M23 connector)

1 3 x M4, 6 [0.24] deep





D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"

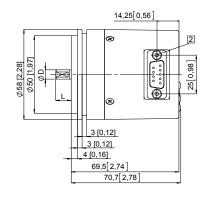
## Synchro flange, ø 58 [2.28]

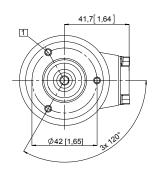
#### Flange type 2 and 4

(drawing with Sub-D connector)

1 3 x M4, 6 [0.24] deep

2 x 4/40 UNC; 3.0 [0.12] deep



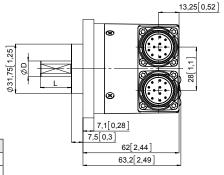


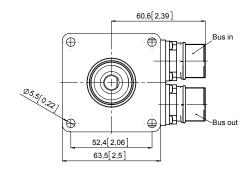
D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"

Square flange, - 63.5 [2.5]

## Flange type 5 and 7

(drawing with 2 x M23 connector)





D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"



# Standard mechanical multiturn, optical

Sendix 5868 / 5888 (shaft / hollow shaft)

**CANopen/CANopenLift** 

### Dimensions shaft version, with fixed connection

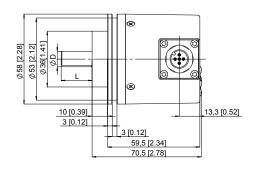
Dimensions in mm [inch]

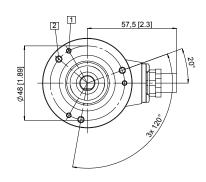
### Clamping flange, ø 58 [2.28] Flange type 1 and 3

(drawing with 1 x M12 connector)

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.32] deep



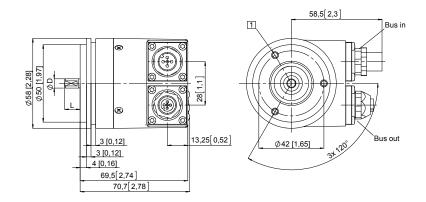


D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"

#### Synchro flange, ø 58 [2.28] Flange type 2 and 4

(drawing with M12 connector)

1 3 x M4, 8 [0.32] deep



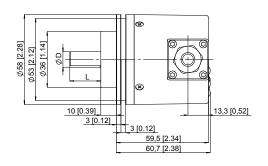
D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"

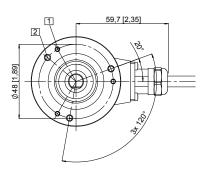
### Clamping flange, ø 58 [2.28] Flange type 1 and 3

(drawing with cable)

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.32] deep





D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"



# Standard mechanical multiturn, optical

Sendix 5868 / 5888 (shaft / hollow shaft)

CANopen/CANopenLift

## Dimensions hollow shaft version (blind hollow shaft), with removable bus terminal cover

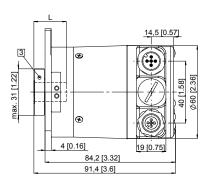
Dimensions in mm [inch]

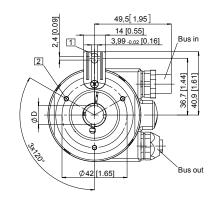
# Flange with spring element, long Flange type 1 and 2

(drawing with 2 x M12 connector)

- Slot spring element recommendation: cylindrical pin DIN 7, ø 4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]
I - insertion death may blind hollow shaft		





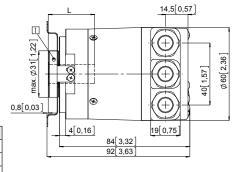
## Flange with stator coupling, ø 63 [2.48] Flange type 5 and 6

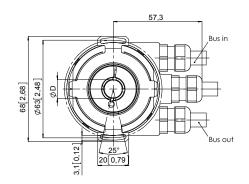
Pitch circle diameter for fixing screws 63 [2.48]

(drawing with cable)

1 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]
L = insertion depth max. blind hollow shaft		





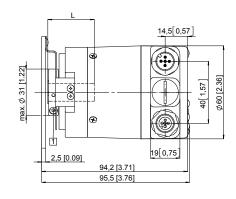
# Flange with stator coupling, ø 65 [2.56] Flange type 3 and 4 $\,$

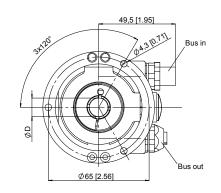
Pitch circle diameter for fixing screws 65 [2.56]

(drawing with 2x M12 connector)

1 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]
L = insertion depth max. blind hollow shaft		







# Standard mechanical multiturn, optical

Sendix 5868 / 5888 (shaft / hollow shaft)

CANopen/CANopenLift

### Dimensions hollow shaft version (blind hollow shaft), with fixed connection

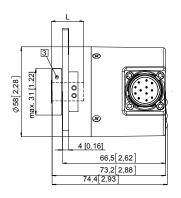
Dimensions in mm [inch]

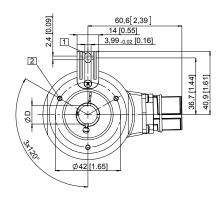
## Flange with spring element, long Flange type 1 and 2

(drawing with M23 connector)

- 1 Slot spring element recommendation: cylindrical pin DIN 7, ø 4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]
L = insertion depth max. blind hollow shaft		



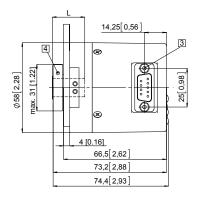


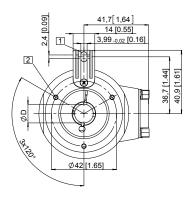
## Flange with spring element, long Flange type 1 and 2

(drawing with Sub-D connector)

- 1 Slot spring element recommendation: cylindrical pin DIN 7, ø 4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 2 x 4/40 UNC; 3.0 [0.12] deep
- 4 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]
L = insertion depth max. blind hollow shaft		





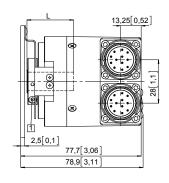
## Flange with stator coupling, ø 65 [2.56] Flange type 3 and 4

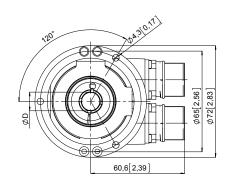
Pitch circle diameter for fixing screws 65 [2.56]

(drawing with 2 x M23 connector)

1 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]
I = insertion denth max_blind hollow shaft		







# Standard mechanical multiturn, optical

Sendix 5868 / 5888 (shaft / hollow shaft)

**CANopen/CANopenLift** 

### Dimensions hollow shaft version (blind hollow shaft), with fixed connection

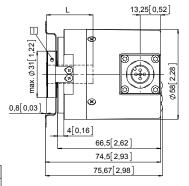
Dimensions in mm [inch]

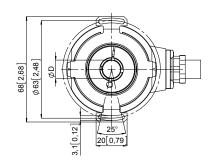
# Flange with stator coupling, ø 63 [2.48] Flange type 5 and 6 $\,$

Pitch circle diameter for fixing screws 63 [2.48]

(drawing with M12 connector)

Recommended torque for the clamping ring 0.6 Nm





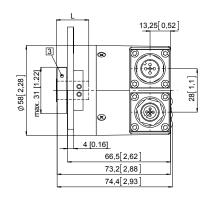
D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]
I = insertion denth max blind hollow shaft		

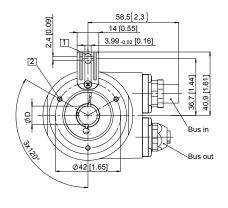
## Flange with spring element, long Flange type 1 and 2

(drawing with 2 x M12 connector)

- Slot spring element recommendation: cylindrical pin DIN 7, ø 4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]
I = insertion denth max blind hollow shaft		





# Flange with stator coupling, ø 65 [2.56] Flange type 3 and 4 $\,$

Pitch circle diameter for fixing screws 65 [2.56]

(drawing with cable)

1 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]
L = insertion depth max. blind hollow shaft		

