

Absolute encoders – multiturn

Compact electronic multiturn, magnetic

Sendix M3663 / M3683 (shaft / hollow shaft)

SSI



The Sendix M36 with Energy Harvesting Technology is an electronic multiturn encoder in miniature format, without gear and without battery. With a size of just 36 x 53 mm it offers a blind hollow shaft of up to 10 mm.



























High rotational

Temperature

High protection

High shaft load capacity

Shock / vibration resistant

Reverse polarity protection

salt spray tested

Harvesting

Reliable and insensitive

- Sturdy bearing construction in Safety-Lock[™] design for resistance against vibration and installation errors.
- · Reduced number of components ensures magnetic insensitivity.
- IP67 protection and wide temperature range -40 °C ... +85 °C.
- · Without gear and without battery, thanks to the Energy Harvesting technology.

Application oriented

- Absolute accuracy ±1°.
- Repeat accuracy ±0.2°.
- Short control cycles, clock frequency with SSI up to 2 MHz.
- Max. resolution 38 bit (14 bit ST + 24 bit MT).

Order code **Shaft version**

8.M3663





then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days $\frac{1}{2}$



a Flange

1 = clamping flange, IP67, ø 36 mm [1.42"]

3 = clamping flange, IP65, ø 36 mm [1.42"]

2 = synchro flange, IP67, ø 36 mm [1.42"]

4 = synchro flange, IP65, ø 36 mm [1.42"]

b Shaft (ø x L), with flat

 $1 = \emptyset 6 \times 12.5 \text{ mm} [0.24 \times 0.49"]$

 $3 = \emptyset 8 \times 15 \text{ mm} [0.32 \times 0.59"]$

 $5 = \emptyset 10 \times 20 \text{ mm} [0.39 \times 0.79"]$ $2 = \emptyset 1/4" \times 12.5 \text{ mm} [0.49"]$

© Interface / supply voltage 2 = SSI / 10 ... 30 V DC

d Type of connection

1 = axial cable, 1 m [3.28'] PUR

A = axial cable, special length PUR *)

2 = radial cable, 1 m [3.28'] PUR

B = radial cable, special length PUR *)

3 = axial M12 connector, 8-pin

4 = radial M12 connector, 8-pin

*) Available special lengths (connection types A, B): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.M3663.432A.G322.0030 (for cable length 3 m)

Code

B = SSI, binary

G = SSI, gray

Resolution (singleturn)

A = 10 bit ST

2 = 12 bit ST

3 = 13 bit ST

4 = 14 bit ST

Resolution (multiturn)

2 = 12 bit MT

6 = 16 bit MT

A = 20 bit MT4 = 24 bit MT

Optional on request

- Ex 2/22 (only for connection types 3 and 4)
- surface protection salt spray tested



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Order code Hollow shaft

 $\begin{array}{c|c} 8.\,M3683 \\ \hline \text{Type} \end{array} \, . \, \, \begin{array}{c|c} X\,X\,2\,X \\ \hline \textbf{0} \, \textbf{0} \, \textbf{0} \end{array} \, . \, \, \begin{array}{c|c} X\,X\,X\,2 \\ \hline \textbf{0} \, \textbf{0} \, \textbf{0} \end{array} \, .$

If for each parameter of an encoder the <u>underlined preferred option</u> is selected, then the delivery time will be 10 working days for a maximum of 10 pieces.

Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

2 = with stator coupling, IP65, ø 46 mm [1.81"]

3 = with spring element, long, IP65

5 = with stator coupling, IP67, ø 46 mm [1.81"]

6 = with spring element, long, IP67

Blind hollow shaft
 (incoming double me)

(insertion depth max. 18.5 mm [0.73"])

1 = Ø 6 mm [0.24"]

3 = Ø 8 mm [0.32"]

4 = ø 10 mm [0.39"]

 $2 = \emptyset 1/4''$

• Interface / supply voltage

2 = SSI / 10 ... 30 V DC

d Type of connection

1 = axial cable, 1 m [3.28'] PUR

A = axial cable, special length PUR *)

2 = radial cable, 1 m [3.28'] PUR

B = radial cable, special length PUR *)

3 = axial M12 connector, 8-pin

4 = radial M12 connector, 8-pin

*) Available special lengths (connection types A, B): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.M3683.242A.G322.0030 (for cable length 3 m)

e Code

B = SSI, binary

G = SSI, gray

• Resolution (singleturn)

A = 10 bit ST

2 = 12 bit ST

3 = 13 bit ST

4 = 14 bit ST

Resolution (multiturn)

2 = 12 bit MT

6 = 16 bit MT

A = 20 bit MT

4 = 24 bit MT

Optional on request

- Ex 2/22 (only for connection types 3 and 4)

- surface protection salt spray tested

Mounting accessory for shaft encoders

Coupling Bellows coupling ø 19 mm [0.75"] for shaft 8 mm [0.32"]

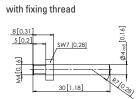
Mounting accessory for hollow shaft encoders Dimensions in mm [inch]

8.0000.1102.0808

8.0010.4700.0000

Torque pin, ø 4 mm

for flange with spring element (flange type 3 + 6)



Cables and connectors

Preassembled cables M12 female connector with coupling nut, 8-pin, A coded, straight open ended

2 m [6.56'] PUR cable

Connectors

M12 female connector with coupling nut, 8-pin, A coded, straight (metal)

Order no.

05.00.6051.8211.002M

05.CMB 8181-0

Further Kübler accessories can be found at: kuebler.com/accessories
Further Kübler cables and connectors can be found at: kuebler.com/connection-technology

Technical data

Mechanical characteristics				
Maximum speed shaft or blind hollow shaft version without shaft seal (IP65)	6000 min ⁻¹ 3000 min ⁻¹ (continuous)			
shaft or blind hollow shaft version with shaft seal (IP67)	4000 min ⁻¹ 2000 min ⁻¹ (continuous)			
Starting torque at 20 °C [68 °F] without shaft seal with shaft seal (IP67	< 0.007 Nm < 0.01 Nm			
Shaft load capacity radial axial	40 N 20 N			

Weight		approx. 210 g [7.41 oz]
Protection acc. to	EN 60529	IP65 or IP67
Working tempera	ture range	-40 °C +85 °C [-40 °F +185 °F]
Materials	shaft / hollow shaft flange housing cable	stainless steel aluminum zinc die-cast PUR
Shock resistance	acc. to EN 60068-2-27	2500 m/s ² , 6 ms
Vibration resistant	e acc. to EN 60068-2-6	300 m/s², 10 2000 Hz



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Electrical characteristics	
Supply voltage	10 30 V DC
Current consumption (no load)	max. 40 mA
Reverse polarity protection of the supply voltage	yes
Short-circuit proof outputs	yes 1)
UL approval	file no. E224618
CE compliant acc. to	EMC guideline 2014/30/EU RoHS guideline 2011/65/EU

SSI interface			
Output driver	RS485 transceiver type		
Permissible load / channel	max. +/- 30 mA		
Signal level HIGH LOW with $I_{Load} = 20 \text{ mA}$	typ 3.8 V typ 1.3 V		
Resolution singleturn	10 14 bit		
Absolute accuracy 2)	±1°		
Repeat accuracy	±0.2°		
Number of revolutions (multiturn)	max. 24 bit		
Code	binary or gray		
SSI clock rate	50 kHz 2 MHz		
Data refresh rate	2 ms		
Monoflop time	≤ 15 µs		

Note: If the clock cycle starts within the monoflop time a second data transfer begins with the same data. If the clock cycle starts after the monoflop time the cycle begins with the new values. The update rate is dependent on the clock speed, data length and monoflop time.

SET input		
Input		active HIGH
Input type		comparator
Signal level (+V = supply voltage)	HIGH LOW	min. 60 % of +V, max: +V max. 30 % of +V
Input current		< 0.5 mA
Min. pulse duration (SET)		10 ms
Input delay		1 ms
New position data readable after		1 ms
Internal processing time		200 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the supply voltage must not be switched off.

The SET function should be carried out whilst the encoder is at rest.

The number of preset value writing cycles is limited to 10,000.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

DIR input

Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

Response time (DIR input) 1 ms

Power-ON

After Power-ON the device requires a time of approx. 150 ms before valid data can be read.

Hot plugging of the encoder should be avoided.

Terminal assignment

Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)									
2 1, 2, A, B SI	SET. DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	÷	
	1, 2, A, D	SEI, DIN	Core color:	WH	BN	GN	YE	GY	PK	BU	RD	shield
Interface	Type of connection	Features	M12 connector, 8	3-pin								

Interface	Type of connection	Features	M12 connector, 8-pin									
2 2.4 CET DID	CET DID	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Ť	
2	3, 4	SET, DIR	Pin:	1	2	3	4	5	6	7	8	PH

+V: Supply voltage encoder +V DC

0 V: Supply voltage encoder ground GND (0 V)

C+, C-: Clock signal
D+, D-: Data signal
SET: Set input
DIR: Direction input

PH ±: Plug connector housing (shield)

Top view of mating side, male contact base



M12 connector, 8-pin

¹⁾ Short circuit proof to 0 V or to output when supply voltage correctly applied.

²⁾ Over the whole temperature range.



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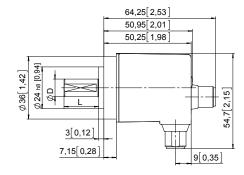
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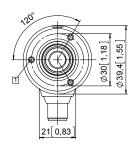
Dimensions shaft version

Dimensions in mm [inch]

Clamping flange, ø 36 [1.42] Flange type 1 and 3

1 3 x M3, 6 [0.24] deep



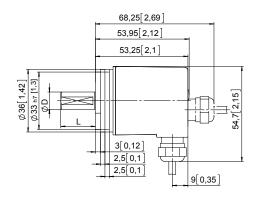


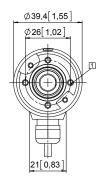
U	l It	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]

Synchro flange, ø 36 [1.42] Flange type 2 and 4

1 4 x M3, 6 [0.24] deep

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]







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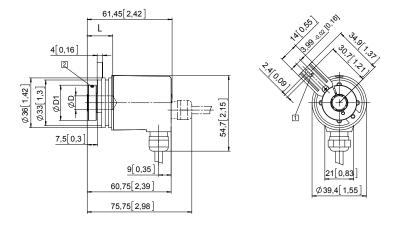
Dimensions hollow shaft version

Dimensions in mm [inch]

Flange with spring element, long Flange type 3 and 6

- Slot spring element, recommendation: torque pin DIN 7, ø 4 [0.16]
- 2 Recommended torque for the clamping ring 0.7 Nm

D	Fit	L	D1			
6 [0.24]	H7	18.5 [0.73]	24 [0.94]			
8 [0.32]	H7	18.5 [0.73]	25.5 [1.00]			
10 [0.39]	H7	18.5 [0.73]	25.5 [1.00]			
1/4" H7 18.5 [0.73] 24 [0.94]						
I = insertion denth max_blind hollow shaft						



Flange with stator coupling, ø 46 [1.81] Flange type 2 and 5

1 Recommended torque for the clamping ring 0.7 Nm

D	Fit	L	D1			
6 [0.24]	H7	18.5 [0.73]	24 [0.94]			
8 [0.32]	H7	18.5 [0.73]	25.5 [1.00]			
10 [0.39]	H7	18.5 [0.73]	25.5 [1.00]			
1/4" H7 18.5 [0.73] 24 [0.94]						
L = insertion depth max. blind hollow shaft						

